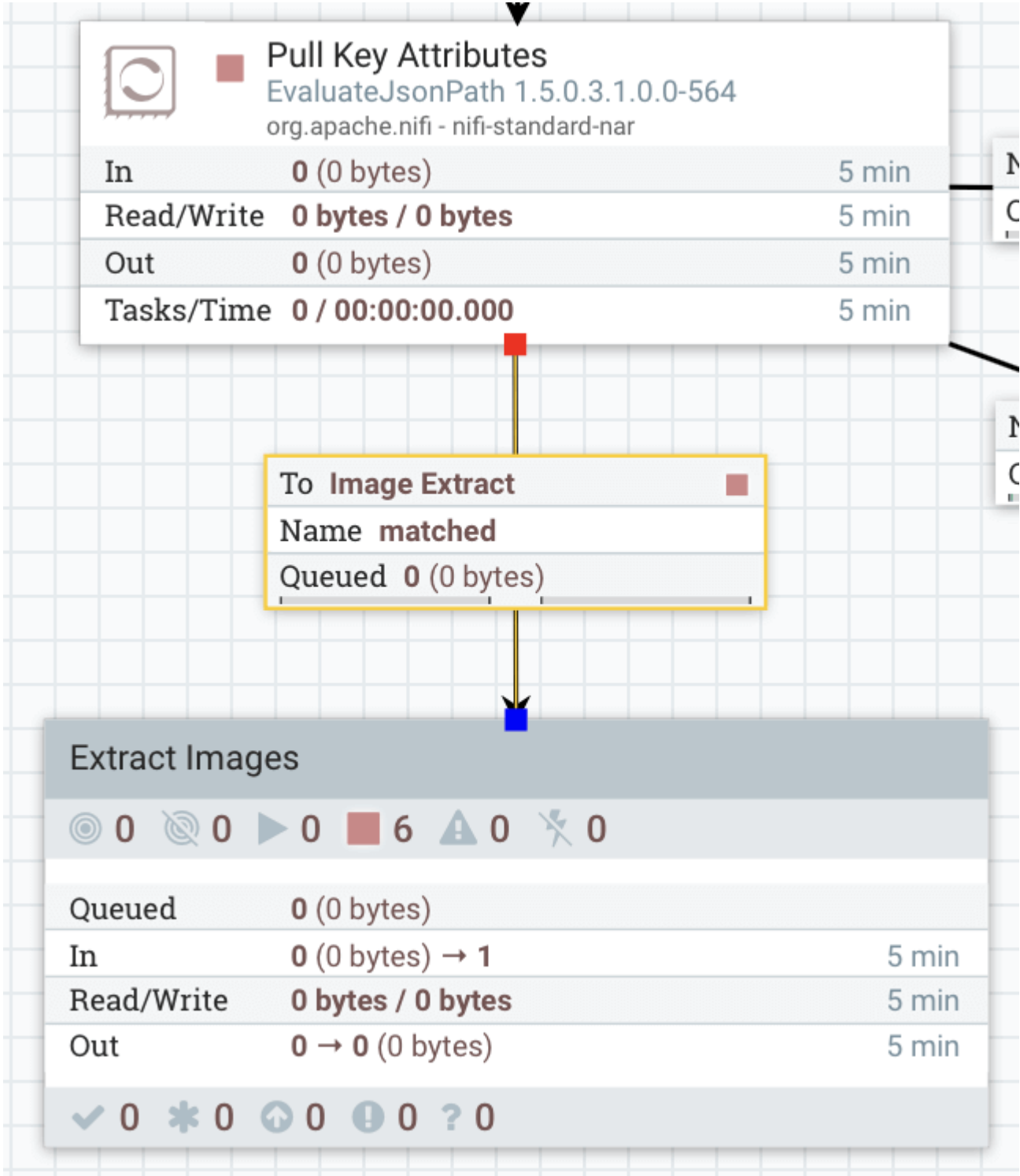


FlashBlade AI



FlashBlade AI FlashBlade AI 1 2 3 FlashBlade Apache Spark Zeppelin Apache Hive

YOLO (You Only Look Once)

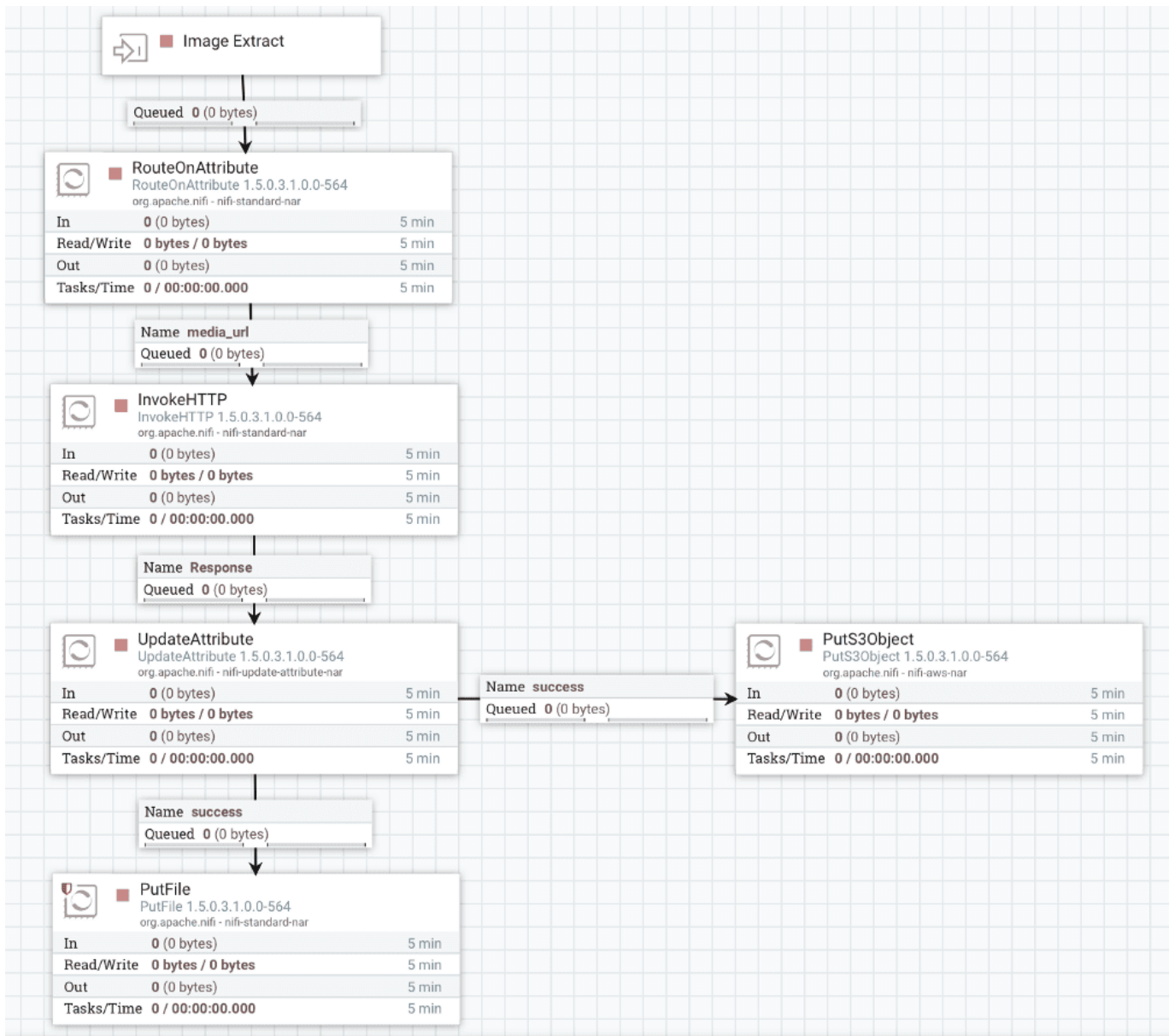
YOLO (You Only Look Once) is a real-time object detection algorithm. It is designed to be fast and accurate, making it suitable for applications where speed is critical.

YOLO is a single-stage detector, meaning it performs object detection in a single pass through the network.

1. Input image is processed by a convolutional neural network.
2. The network outputs a grid of bounding boxes and confidence scores.
3. Non-Maximum Suppression (NMS) is used to filter out overlapping bounding boxes.
4. The final output is a set of bounding boxes and class probabilities.
5. The algorithm is trained on a dataset of images with bounding boxes and class labels.

YOLOv2 (You Only Look Once version 2)

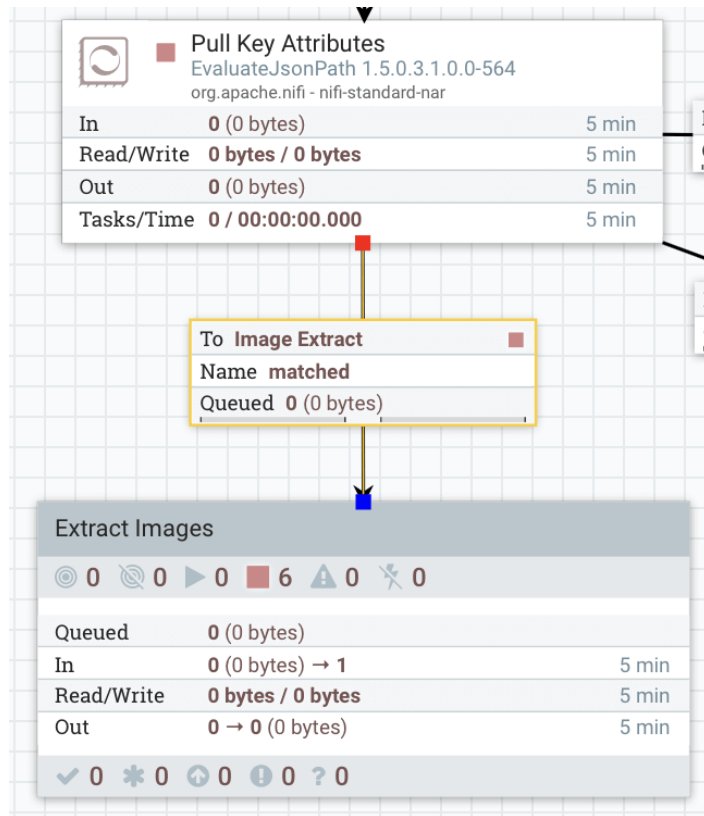
YOLOv2 (You Only Look Once version 2) is an improved version of the original YOLO algorithm. It introduces several key changes to enhance performance and accuracy.



1. NiFi 工作流

工作流描述：NiFi 通过 HTTP 从 FlashBlade NFS 提取数据，通过 S3 存储，并写入文件。

NiFi UI 中 Extract Images 工作流配置：Pull Key Attributes 提取 Images 属性，matched 属性。



2 Extract Images

NiFi FlashBlade NFS S3 Apache Ambari S3 Viewer

Ambari hortonworks Dashboard Services Hosts Alerts Admin admin

/ > images > dogs Showing 5000 files or folders of 44600

Search in current directory...

Name	Size	Last Modified	Owner	Group	Permission
DTVoZ9yV4AAvFj4.jpg	95.2 kB	2018-11-05 13:19	admin	admin	-rw-rw-rw-
5ferkEvqPOJuLj8.jpg	63.3 kB	2018-11-05 13:19	admin	admin	-rw-rw-rw-
ByNN0JauWV4vuh.jpg	71.6 kB	2018-11-05 13:19	admin	admin	-rw-rw-rw-
4QhPHY_GOODhkLFB.jpg	18.4 kB	2018-11-05 13:18	admin	admin	-rw-rw-rw-
6cFNJ1CwBNnc5M6U.jpg	20.2 kB	2018-11-05 13:18	admin	admin	-rw-rw-rw-
DSm_xoNPszOZOUvD.jpg	51.5 kB	2018-10-31 11:43	admin	admin	-rw-rw-rw-
DdU6yS6UQAEAXA-.jpg	74.7 kB	2018-10-31 11:43	admin	admin	-rw-rw-rw-
1jdfPLzL_cgHooYm.jpg	36.0 kB	2018-10-31 11:43	admin	admin	-rw-rw-rw-

3 Ambari S3 Viewer

YOLOv4

YOLOv4 是 YOLO 系列中性能最强、速度最快的版本。它通过引入 C2 和 C3 模块，以及引入 SPP 和 CBAM 模块，显著提升了模型的检测性能。YOLOv4 在 COCO 数据集上达到了 47.6% 的 mAP，在推理速度上也保持了领先。本文将介绍 YOLOv4 的架构、训练和部署。

YOLOv4 的架构与 YOLOv3 类似，但引入了 C2 和 C3 模块。C2 模块包含两个 C2f 子模块，每个子模块由两个 C2 块组成。C3 模块包含两个 C3f 子模块，每个子模块由两个 C3 块组成。SPP 和 CBAM 模块分别用于空间池化和通道注意力。YOLOv4 的训练和部署可以通过 Jupyter 进行。

This loads the weights of a trained YOLO model. Here's a summary of the layers our model contains.

```
In [2]: yolo_model.summary()
batch_normalization_65 (BatchNo (None, None, None, 5 2048 conv2d_66[0][0])
batch_normalization_72 (BatchNo (None, None, None, 2 1024 conv2d_74[0][0])
leaky_re_lu_58 (LeakyReLU) (None, None, None, 1 0 batch_normalization_58[0][0])
leaky_re_lu_65 (LeakyReLU) (None, None, None, 5 0 batch_normalization_65[0][0])
leaky_re_lu_72 (LeakyReLU) (None, None, None, 2 0 batch_normalization_72[0][0])
conv2d_59 (Conv2D) (None, None, None, 2 261375 leaky_re_lu_58[0][0])
conv2d_67 (Conv2D) (None, None, None, 2 130815 leaky_re_lu_65[0][0])
conv2d_75 (Conv2D) (None, None, None, 2 65535 leaky_re_lu_72[0][0])
-----
Total params: 62,001,757
Trainable params: 61,949,149
Non-trainable params: 52,608
```

YOLOv4 部署

YOLOv4 模型在 NVIDIA Jetson Nano 上部署时，需要配置 GPU 加速。可以通过修改配置文件来指定 GPU 设备。FlashBlade 是一种高性能的存储解决方案，可以用于存储模型和数据。

部署环境

部署环境需要安装 Python 3.7 及以上版本，以及 TensorFlow 2.4 及以上版本。REST API 提供了一种方便的方式来调用模型。API 文档可以在项目仓库中找到。

REST API 部署

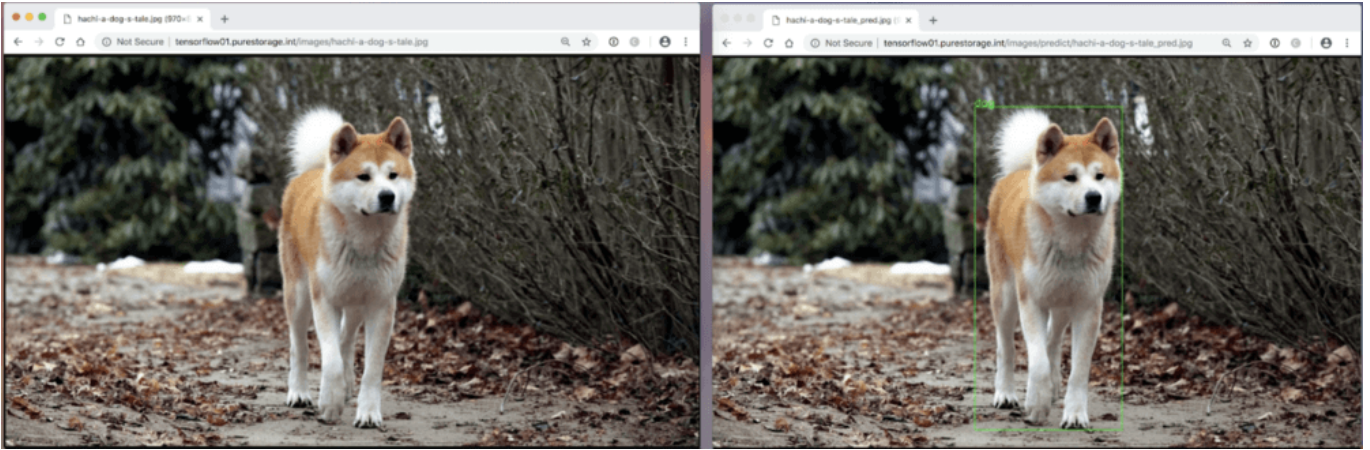
Python 部署 YOLOv4 模型，可以通过 HTTP 接口进行调用。

[crayon-6424c64a9f978019509656/]

API 部署在 localhost:8080 上，可以通过 REST API 进行调用。

[crayon-6424c64a9f97b433536522/]

API 部署在 98 端口上，可以通过 REST API 进行调用。部署环境需要配置 GPU 加速。



5
HACHI

Raspberry Pi [Intel Neural Compute Stick 2](#) [Google Edge Tensor Processing Unit](#)

FlashBlade AI HDD DAS GPU HPC

FlashBlade

FlashBlade

FlashBlade AI

FlashBlade AI 1

FlashBlade AI 2 —

FlashBlade AI 3 —